APP4RTA

For Analyzing Response Time & End-to-End Chain Latency

Source: <u>https://gsoc-doc.readthedocs.io/en/latest/contents/ui.html</u>

1. APP4RTA Location



Run 'APP4RTA.java' in 'org.eclipse.app4mc.gsoc_rta.ui' package.

2. Search Amalthea

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Amalthea Mode	d PU Num	Search	Amaithea			AI	9948	× ??7A
EVENT CHAIN	MODEL	Calcul	ate Reset					
	Reaction (Implicit)		Reaction (LET)	Task Chain >				
Best-Case		Best-Case						
Worst-Case		Worst-Case						
Bost-Caco	Initial Reaction (Implicit)	Best-Case	Initial Reaction (LET)					
Worst-Case		Worst-Case						
const case	Age (Implicit)	troibe cabe	Age (LET)					
Best-Case	inge (inspireit)	Best-Case						
Worst-Case		Worst-Case						
	Single-core Initial Reaction		Single-core Worst-case Reaction					
Critical-Case		Critical-Case	Congre core resist case Adaction					
Best-Case		Best-Case						
Worst-Case		Worst-Case						

Based on the horizontal line on the middle, the upper part is for response time and mapping analysis and the lower part is for end-to-end event chain latency analysis. The first thing to do is deciding a target Amalthea model. Click the 'Search Amalthea' button.

3. Navigate to The Amalthea Folder

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Amalthea Model Task Name PU No	lum	Search A	Amalthea		BREARTS
		Fill	Open File ok In: app4mc.example.tool.ja settings bin MFTA.INF model-Input src xtend.gen e Name: es of Type: Amaithea models	va va a a a a a a a a a a a a a a a a a	
EVENT CHAIN MODE	EL	Calcula	ate Reset		
React	ction (Implicit)		Reaction (LET)	Task Chain >	
Best-Case		Best-Case			
Worst-Case		Worst-Case			
Best-Case	ai Reaction (Implicit)	Best-Case	Initial Reaction (LET)		
Worst-Case		Worst-Case			
Age ((Implicit)		Age (LET)		
Best-Case		Best-Case			
Worst-Case		Worst-Case			
Singl	le-core Initial Reaction		Single-core Worst-case Reaction	ı.	
Critical-Case		Critical-Case			
Best-Case		Best-Case			
Worst-Case		Worst-Case			

Navigate to the folder where the target Amalthea model file is located.

4. Select & Open Amalthea

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Amalthea Mode Task Name	l PU Num	Search	Amalthea Open File Open File Open File ChallengeModel_TCs.amxml	×	APP4RTA
		FI	le Name: ChallengeModel_TCs.a les of Type: Amalthea models	mxmi Open Cncel 2	
EVENT CHAIN	MODEL	Calcul	ate Reset		
Death Grand	Reaction (Implicit)	Deet Co	Reaction (LET)	Task Chain >	
Best-Case		Best-Case			
fronse cuse	Initial Reaction (Implicit)	Worst Cuse	Initial Reaction (LET)		
Best-Case		Best-Case			
Worst-Case		Worst-Case			
	Age (Implicit)		Age (LET)		
Best-Case		Best-Case			
Worst-Case		Worst-Case			
	Single-core Initial Reaction		Single-core Worst-case Reaction		
Critical-Case		Critical-Case			
Best-Case		Best-Case			
Worst-Case		Worst-Case			

Select and open an Amalthea file. In this example, a multi-core Amalthea model is chosen.

5. Amalthea Model Loaded

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Amalthra Moon	ChallengeModel_TCs.a	mxmi Search	Amalthea			APP4RTA
Tark Name OS_Overhead Udar_Grabber ASM CANbus_polling EKF Planner PRE_SFM_gpu PRE_Localizati. PRE_Localization Lane_detection Detaction	Pt Num Defualt IA Enter IA Synchronous Synchronous Asynchronous Worst-Case Best-Case Best-Case Best-Case Calculate Reset Schedulability Cumulated Memory- Cumulated Memory- Cumulated Schedulability Cumulated Schedulability Cumulated Schedulability Cumulated Schedulability Schedulability Cumulated Schedulability Schedulability Cumulated Schedulability Schedulability Cumulated Schedulability Schedulability Schedulability	0: Di 4: Al Access Cost	enver Besponse Time	1: Denver Response Time	2: A57 Response Time	3: ASZ Response Time
EVENT CHAIN	MODEL	✓ Calcul	ate Reset			
Best-Case Worst-Case	Reaction (Implicit)	Best-Case Worst-Case	Reaction (LET)	Task Chain >		
Best-Case	Initial Reaction (Implicit)	Best-Case	Initial Reaction (LEI)			
Worst-Case		Worst-Case				
Best-Case Worst-Case	Age (Implicit)	Best-Case Worst-Case	Age (LET)			
	Single-core Initial Reaction	n	Sinale-core Worst-case	Reaction		
Critical-Case		Critical-Case				
Best-Case		Best-Case				
Worst-Case		Worst-Case				

After a model is loaded, it shows all the tasks (1) and processing units (2) that the selected model has.

6. Integer Mapping

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Amalthea Model ChallengeModel_1	Cs.amxmi Search	Amalthea						APP4R	TA .
Task Name Pl Num OS Overhead 4 Defualt 10	0: D	enver Respons	e Time 1: Denve	er Response Time	2: A57	Response Time	3: A57	Response	Time
Lidar_Grabber	/'								
DASM 1 CANbus_polling 3 Synchronou									
EKF 4	15								
Planner 0 Worst-Case	e								
PRE_Localizati. 3	4: A	.57 Response	e Time 5: A57	Response Time	6: GPU_def	Response Time			
PRE_Lane_det. 3 Calculate									
SFM 6									
Localization 2 Schedulability									
Detection 6 Cumulated Men	ory-Access Cost								
Cumulated Con	ention								
2									
Computation									
Response Time	Sum								
EVENT CHAIN MODEL	▼ Calcu	late Reset							
Reaction (Implicit) Best-Case	Best-Case	Reaction (LET)		Task Chain >					
Worst-Case	Worst-Case								
Initial Reaction (Impl	cit)	Initial Reaction (LET)						
Worst-Case	Worst-Case								
Age (Implicit)		Age (LET)							
Best-Case	Best-Case								
Worst-Case	Worst-Case								
Single-core Initial Rea	ction	Single-core Worst	-case Reaction						
Critical-Case Best-Case	Critical-Case								
	Dest cuse								

When the 'Default IA' (1) button is clicked, each task's box (2) is automatically filled with an integer number. This indicates that a task is about to be mapped to the corresponding identity number of processing unit. One can also write an integer number in each box manually. The 'Default IA' means an integer array to map all the tasks to processing units and that is specifically designed to make the '*ChallengeModel_TCs.amxmi*' model schedulable. Therefore it is always possible that it does not serve for other multi-core models. However, the 'Default IA' would only contain numbers of 0 when a single-core model is loaded.

7. Assign Tasks to Processing Units

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Amalthea Model	C	hallengeModel_TCs.amxm	i [Search	Amalthea						1	PP4R	17/A
Task Name OS_Overhead Lidar_Grabber DASM CANbus_polling EKF Planner PRE_SFM_gpu PRE_Localizati PRE_Lane_det PRE_Detection SFM Localization Lane_detection Detection	PU Num 4 1 1 3 4 0 3 3 0 6 2 5 6	Defualt IA Enter IA Synchronous Asynchronous Worst-Case Average-Case Best-Case Calculate Reset Schedulability Cumulated Memory-Acces Cumulated Contention Computation Response Time Sum	ss Cost	0: D Plate Providence Plate Pl	enver Kespo	nse Time	1: Denver DASM Lidar_Grabbe	Response Time r Response Time 0	2: A57 Localization 6: GPU_def SFM Detection	Response Time Response Time	CANbus pol PRE_SFM_C PRE_Lane_C PRE_Localiz	Response	Time
EVENT CHAIN M				Calcul	ate Reset	1							
	Reactio	n (Implicit)		Calcul	Reaction (LET)		Та	sk Chain S					
Best-Case		(implicity	Best	-Case	ficture (LDT)								
Worst-Case			Wors	st-Case									
1	Initial	Reaction (Implicit)	-		Initial Reaction	n (LET)							
Best-Case			Best	-Case									
worst-Case			wors	st-Case									
Rest-Case	Age (In	nplicit)	Res	Case	Age (LET)								
Worst-Case			Wors	t-Case									
Worst-Case	Single-	core Initial Reaction		it-Case	Single-core Wo	erst-case Re	action						
Critical-Case			Critic	al-Case									
Best-Case			Best	-Case									
Worst-Case			Wors	st-Case									

When the 'Enter IA' (1) button is clicked, each task is mapped to the corresponding processing unit (2). Since there are 7 processing units in the '*ChallengeModel_TCs.amxmi*' model, it shows 7 pairs of lists. The list on the left side of each pair is for listing names of the tasks that are mapped to the corresponding processing unit while one on the right side is for listing response times of the corresponding tasks.

8. Measure Response Time

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Amalthea Mode	ChallengeModel_TCs.amxmi	Search Amalt	iea					1	PP4R	TA
Task Name OS_Overhead Lidar_Grabber DASM CANbus_polling EKF Planner PRE_SFM_gpu. PRE_Localizati. PRE_Lane_det. PRE_Detection. SFM Localization Lane_detection Detection	PU Num 4 Defualt IA 1 Enter IA 3 Synchronous 4 Asynchronous 5 Worst-Case 3 Average-Case 3 Average-Case 3 Average-Case 3 Caiculate 5 Smedulability 5 Schedul Cumulated Memory-Access 5 Statedul Cumulated Memory-Access 5 Statedul Cumulated Contention 24795711 Computation 6 65232421	0: Denver Planner PRS_Deta 4: A57 EKF OS_Overh ablel :) 6 Cost 3000 ps 5000 ps 5500 ps	Resolution Non-State 13358534500 173565439500 Non-State Non-State Response Time Non-State ead 4788430000 p 73942150000 Non-State	1: Denver DASM Lidar_Grabber 5: A57 Lane_detectio	Response Time 1302430000 p 18265272000 C > Response Time 56045200000 C > 4	2: A57 Localization 6: GPU_def SFM Detection	Response Time 39259009750C Response Time 200000000 p 200000000 p	CANbus_por PRE_SFM_ PRE_Lane_ PRE_Localiz	Response 60288000 p 20.71995 e 0 p 0 p 0 p	Time 0 ps 0000 1 Tar Tar
EVENT CHAIN	MODEL	Calculate	Reset							
Best-Case Worst-Case	Reaction (Implicit)	Reac Best-Case Worst-Case	tion (LET)	Tas	k Chain >					
Best-Case	Initial Addition (Implicity)	Best-Case	a reaction (LLT)							
Worst-Case		Worst-Case								
Best-Case	Age (Implicit)	Age Best-Case	(LET)							
Worst-Case		Worst-Case								
	Single-core Initial Reaction	Sing	le-core Worst-case Re	eaction						
Critical-Case		Critical-Case								
Best-Case		Best-Case								
Worst-Case		Worst-Case								

(1) Choose the offloading mode between '*Synchronous*' case and 'Asynchronous' case. (2) Choose the execution case between '*Worst-*', '*Average-*', and '*Best-Case*'. (3) By clicking the '*Calculate*' button, each task's response time is calculated and printed on the right list of each list pair (4). All analysis results appear in (5) which include: '*Schedulability*', '*Cumulated Memory-Access Cost'*, '*Cumulated Contention*', '*Computation*', and '*Response Time Sum*'.

9. Task Chain Analysis

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Amalthea Model	ChallengeModel_TCs.amxmi	Search Amalthea	a						PP4R	T A
Task Name PU I OS_Overhead 4 Lidar_Grabber 1 DASM 1 CANbus_polling 3 EKF 4 Planner 0 PRE_SFM_gpu 3 PRE_Localization 9 SFM 6 Localization 2 Lane_detection 6	Aumo Defualt IA Enter IA Synchronous Synchronous Synchronous Synchronous Synchronous Synchronous Best-Case Best-Case Best-Case Calculate Reset Schedulability Schedulability Cumulated Memory-Access Cf 5361668000 Cumulated Contention 2479571000 Computation 63507505050 Response Time Sum	0: Denver Planner PRE_Detect 4: A57 EKF OS_Overheal 00 ps 10 ps	Response Time 13358534500 73565439500 < > > Response Time d 4788430000 p 73942150000 < > >	1: Denver DASM Lidar_Grabber 5: A57 Lane_detectio	Response Time 1302430000 p 18265272000 < > Response Time 56045200000 < >	2: A57 Localization 6: GPU_def SFM Detection	Response Time 39259009750C <	3: A57 CANbus_po PRE_SFM_ PRE_Lane_ PRE_Localit	Response iir 60288000 gp 26771999 de 0 ps (GP ≥ 0 ps (GP > <	1 Time 10 ps 5000 U Tat U Tat V Tat
EVENT CHAIN MOD Rea Best-Case Worst-Case Worst-Case Best-Case Worst-Case	66523242850 Li Li-Lo-EK-P-DA ction (Implicit) 402348334000 ps 893304764000 ps ial Reaction (Implicit) 402348334000 ps ial Reaction (Implicit) 402348334000 ps 528956430000 ps 528956430000 ps ple-core Initial Reaction Not Single-Core.	00 ps 2 Reacting Best-Case Worst-Case Worst-Case Worst-Case Best-Case Worst-Case Single- Critical-Case Best-Case	Reset Int (LET) 468000000 931000000 Reaction (LET) 468000000 536000000 ET) 5000000 ET) 5000000 Core Worst-case R Not Single	Tas 000 ps 000 ps 0000 ps 000 ps 0000 ps 00000 ps 0000000000	sk Chain > 1: Ci Lida 2: Ci Loc 3: Ci EKF 4: Ci Plan 5: Ci DAS	ore1 (Denver) ar_Grabber ore2 (A57) alization ore4 (A57) = ore0 (Denver) nner ore1 (Denver) SM		3		
Worst Case	Not Single-Core.	Worst-Case	Not Single	Core.						

Now that every task's response time is measured, it is possible to measure end-to-end task chain latency with the derived task response times. (1) To analyze end-to-end task chain latency, a task chain in the combo-box should be selected first. (2) Click the *'Calculate'* button, then the selected task chain would be illustrated (3) and all measurement results would also be printed out (4)(5). Since the observed Amalthea model is a multi-core model here, the single-core analysis results are not available (5).

10. Change The Model

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Amalthea Model	ChallengeModel_TCs.amxmi	Search Ar	maithea 1			APP4RTA
Task Name PU OS_Overhead [Lidar_Grabber [DASM [CANbus_polling [EKF [Planner [PRE_SFM_gpu [PRE_Localizati [PRE_Detection [SFM [Localization [Lane_detection [Num	0: Den Plann PRE_ 4: A57 4: A57 EKF OS_C 5: Cost 1000 ps 1500 ps	ver Response Time er Detectio 73565439500 Copen File Look la: WATERST ChallengeModel_Sir File Name: Challeng Files of Type: Amathe	1: Denver Response Time DASM 1302430000 p Lidar_Grabber 18265272000 s_simpleTCs s rgleTCs.amxml 2	2: A57 Response Til Localization 3925900975 X Til 100 100 100 100 100 100 100 10	and 3: A57 Response Time CANbus_pollir 602880000 ps p PRE_SFM_pp 26771995000 p PRE_Lane_de 0 ps (GPU Ta: 0 ps (GPU Ta: PRE_Localiza 0 ps (GPU Ta: 0 ps (GPU Ta: > > > >
	665232428	500 ps		3 (Open Gancel	
EVENT CHAIN MO	DEL LI-LO-EK-P-DA	▼ Calculat	e Reset			
Re	action (Implicit)	k	Reaction (LET)	Task Chain > 1:	Core1 (Denver)	
Best-Case	402348334000 ps	Best-Case	468000000	000 ps	dar_Grabber	
Worst-Case	893304764000 ps	Worst-Case	931000000	000 ps 2:	Core2 (A57)	
Ini	itial Reaction (Implicit)	I	nitial Reaction (LET)	3	Core4 (A57)	
Best-Case	402348334000 ps	Best-Case	468000000	EF	(F	
worst-case	898304764000 ps	worst-case	536000000	4:	Core0 (Denver)	
Ag Best-Case	e (Implicit) 475000000 pc	A Best-Case	Age (LET) 50000000	PI	anner	
Worst-Case	528956430000 ps	Worst-Case	425000000	5: 000 ps	Core1 (Denver)	
	020000000 pa		425000000	D	9.5M	
Su Cultical Case	ngle-core Initial Reaction	Subtract Care	Single-core Worst-case Re	action		
Rost Case	Not Single-Core.	Rost Case	Not Single	-Core.		
Best-Case	Not Single-Core.	Best-Case	Not Single	-Core.		
worst-Case	Not Single-Core.	worst-Case	Not Single	-Core.		

It is possible to change the observed model without clicking the *'Reset'* buttons. Apply the same process but this time with the *'ChallengeModel_SingleTCs.amxmi'* file that is a single-core Amalthea model (1) (2) (3).

11. Single-core RTA

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Amalthea Model Task Name Task0 Task1 Task1 Task3	ChallengeModel_SingleTCs.ar	eable! :) Cost O ps 0000 ps	Amatthea			<i>APP4RTA</i>
EVENT CHAIN I	MODEL	 Calcula 	ate Reset			
	Reaction (Implicit)		Reaction (LET)	Task Chain >	1: Core1 (Denver)	
Best-Case	402348334000 ps	Best-Case	46800000000 ps		Lidar_Grabber	
Worst-Case	893304764000 ps	Worst-Case	93100000000 ps		2: Core2 (A57)	
	Initial Reaction (Implicit)		Initial Reaction (LET)		Localization	
Best-Case	402348334000 ps	Best-Case	46800000000 ps		S: COTE4 (AS7) EKF	
Worst-Case	898304764000 ps	Worst-Case	53600000000 ps		4: Core0 (Denver)	
	Age (Implicit)		Age (LET)		Planner	
Best-Case	475000000 ps	Best-Case	500000000 ps		5: Core1 (Denver)	
Worst-Case	528956430000 ps	Worst-Case	42500000000 ps		DASM	
	Single-core Initial Reaction		Single-core Worst-case Reaction			
Critical-Case	Not Single-Core.	Critical-Case	Not Single-Core.			
Best-Case	Not Single-Core.	Best-Case	Not Single-Core.			
Worst-Case	Not Single-Core.	Worst-Case	Not Single-Core.			

The *'ChallengeModel_SingleTCs.amxmi'* model only has one processing unit with four tasks. As it is already mentioned, the 'Default IA' only contains numbers of 0 because a single-core model is loaded this time. The process is the same.

12. Single-core Task Chain Analysis

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Amalthea Model Task Name PU Task0 (Task1 (Task2 (Task3 (ChallengeModel_SingleTCs.at Num Defualt IA Defualt	eable! :) Cost Ops 0000 ps	Amalthea 57 Respon 60 10000 120000 1 20000 1 20000 1 20000 1 2 2 2 2	se Time 0000000 0000000 0000000 >			₿₽.	0 <i>24RTA</i>
EVENT CHAIN MOI	DEL IEC 10.5.6.3	Calcut	ate Reset					
Rei	action (Implicit)	Curcus	Reaction (LET)		Task Chain >	1: Core() (A57)		
Best-case	Not Multi-Core.	Best-Case		Not Multi-Core.		Task3		
Worst-Case	Not Multi-Core.	Worst-Case		Not Multi-Core.		2: Core0 (A57)		
Ini	tial Reaction (Implicit)		Initial Reaction	(LET)		Task1		
Best-Case	Not Multi-Core.	Best-Case		Not Multi-Core.		3: Core0 (A57)		
Worst-Case	Not Multi-Core.	Worst-Case		Not Multi-Core.		Task2		
Ag	e (Implicit)		Age (LET)			4: Core0 (A57) Task0		
Lest-Case	Not Multi-Core.	Best-Case		Not Multi-Core.		Tasko		
Worst-Case	Not Multi-Core.	Worst-Case		Not Multi-Core.				
ci.	ada-cora Initial Paaction		Single-core Wor	et-casa Panction				
Critical-Case	1600000000000 ps	Critical-Case	190	000000000000 ps				
Best-Case	809000000000 ps	Best-Case	150	000000000 ps				
Worst-Case	1600000000000 ps	Worst-Case	230	0000000000 ps				

Now that every task's response time is measured, it is possible to measure end-to-end task chain latency with the derived task response times. The process is the same. However, a single-core model is analyzed this time. Therefore, latency results regarding single-core are only available while multi-core results are not in this case.